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मानक

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IS 13365-3 (1997): Quantitative classification system of rock mass-Guidelines, Part 3: Determination of slope mass rating [CED 48: Rock Mechanics]



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IS 13365 (Part 3) : 1997 (Reaffirmed - 2012)

### भारतीय मानक

## शैल संहति मात्रात्मक वर्गीकरण तंत्र — मार्गदर्शी सिद्धांत

### भाग 3 ढलान संहति रेटिंग ज्ञात करना

### Indian Standard

## QUANTITATIVE CLASSIFICATION SYSTEM OF ROCK MASS — GUIDELINES

PART 3 DETERMINATION OF SLOPE MASS RATING

ICS 93.020

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#### **BUREAU OF INDIAN STANDARDS** MANAK BHAVAN, 9 BAHADUR SHAH ZAFAR MARG NEW DELHI 110002

November 1997

#### FOREWORD

This Indian Standard was adopted by the Bureau of Indian Standards, after the draft finalized by the Rock Mechanics Sectional Committee had been approved by the Civil Engineering Division Council.

Slope mass rating (SMR) is a measure of degree of stability of rock slopes. The determination of slope mass rating is very easy and yet reliable. This method is recommended for landslide hazard zonation for feasibility studies in the hilly areas where rock is exposed.

Slope mass rating takes into account orientation of joints, seepage forces, fracture spacing, degree of weathering and method of excavation. It also considers mode of failures, for example, Planar slide, wedge slide and toppling failure.

Detailed study of rock slopes is needed if SMR is found to be less than 60 or slope appears to be in distress.

Technical Committee responsible for the formulation of this standard is given in Annex A.

In reporting the results of a test or analysis made in accordance with this standard, if the final value, observed or calculated, is to be rounded off, it shall be done in accordance with IS 2 : 1960 'Rules for rounding off numerical values (*revised*)'.

### Indian Standard

## QUANTITATIVE CLASSIFICATION SYSTEM OF ROCK MASS — GUIDELINES

#### PART 3 DETERMINATION OF SLOPE MASS RATING

#### 1 SCOPE

1.1 This standard (Part 3) covers the procedures for obtaining the value of slope mass rating (SMR) for preliminary assessment of the stability of rock slopes. The approach is based on modification of RMR system using adjustment factors related to discontinuity orientation with reference to slope as well as failure mode and slope excavation methods.

#### **2 REFERENCES**

The Indian Standards given below contain provisions which through reference in this text, constitute provision of this standard. At the time of publication, the editions indicated were valid. All standards are subject to revision, and parties to agreements based on these standards are encouraged to investigate the possibility of applying the most recent editions of the standards indicated below:

IS No. Title

- 8764: 1978 Method of determination of point-load strength index of rocks
- 11315 Method for quantitative description of discontinuities in rock mass:
- (Part 1): 1987 Orientation
- (Part 2): 1987 Spacing
- (Part 4): 1987 Roughness
- (Part 8): 1987 Seepage
- (Part 11): 1987 Core recovery and rock quality designation
- 13365 Quantitative classification sys-(Part 1): 1997 tems of rock mass — Guidelines : Part 1 Rock mass rating (RMR) for predicting engineering properties

#### **3 PROCEDURE**

#### 3.1 Estimation of Rock Mass Rating (RMR basic)

The geomechanical properties of rock mass shall be evaluated by RMR system. The RMR basic shall be determined by adding the rating values for the following five parameters as given in Table 1. The procedure has been elaborated in detail in IS 13365 (Part 1).

- a) Uniaxial compressive strength of intact material (see IS 8764)
- b) Rock quality designation (RQD) [see IS 11315 (Part 11)]
- c) Spacing of discontinuities [see IS 11315 (Part 2)]
- d) Condition of discontinuities [see IS 11315 (Part 4)]
- e) Ground water conditions [see IS 11315 (Part 8)]

## 3.2 Determination of Failure Modes in Rock Slopes

The slope failures in rock mass are governed by geological discontinuities and movement occurs along surfaces formed by one or several sets of geological discontinuities. Basic modes of failures are given in IS 11315 (Part 1) and summarised below.

#### 3.2.1 Plane Failure (Plain Wedge Slide)

Plane failure takes place along continuous joints dipping towards the slope or valley with strike nearly parallel to the slope face [Fig. 1(a)]. The instability conditions occur if critical joint dips less than slope, and the mobilised shear strength along the joint is not enough for stability.

#### 3.2.2 Wedge Failure (3D Wedge Slide)

Wedge failure takes place along two geological discontinuities of different sets, whose line of intersection is towards the slope or valley, but the plunge is less than the inclination of the slope [Fig. 1(b)]. It is generally more frequent than the planer slides.

It may be noted that plane failure is a special case of wedge failure.

### Table 1 RMRbasic Rating

(Clause 3.1)

Parameter	ameter RANGES OF VALUES							
Strength of in-	Point Load Strength Index	>10 Mpa	4-10 MPa	2-4 MPa	1-2 MPa	<1 MPa for this low range uniaxial compressive test is preferred		ange ressive red
rock	Uniaxial Compressive Strength	>250 Mpa	100-250 MPa	50-100 MPa	25-50 MPa	5-25 MPa	1-5 MPa	< 1 MPa
Rating	·	15	12	7	4	2	1	0
Drill core quality	RQD	90-100%	75-90%	50-75%	25-50%		<25%	, ,
Rating		20	17	13	8		3	
Spacing of discontinuities		> 2 m	0.6-2 m	200-600 mm	60-200 mm	•	<60 mm	۱ 
Rating	····	20	15	10	8		5	
Condition of discontinuities		Very rough surfaces. Not continuous. No separation. Unweathered wall rock.	Slightly rough surfaces. Separation < 1 mm slightly weathered walls.	Slightly rough surfaces . Separation < 1 mm highly weathered walls.	Slickensided surfaces, or Gouge < 5 mm thick or separation 1-5 mm continuous.	Self C ( separ- contin	iouge : DR ation >: nuous	>5mm 5 mm
Rating		30	25	20	10	0		
Ground water condition	,	Completely dry	Damp	Wet	Dripping	Flowi	ng	
Rating		15	10	7	4	0		

#### 3.2.3 Toppling Failure

Toppling failure takes place along a continuous set of joints which dips against the slope, and with strike nearly parallel to slope face [Fig. 1(c)]. Joints are generally weathered in these cases. In practice, two kinds of instability can happen, that is, minor toppling near the surface of slope, and deep toppling which can produce large deformations. In both the cases the failures develop slowly, and are not prone to sudden rock falls.

#### 3.2.4 Collection of Field Data

The determination of failure modes in rock slopes shall be done on the basis of graphical analysis of the geological discontinuities observed on the slope. Depending upon the structural complexity of the area, 100 to 500 readings of the geological discontinuities shall be taken, the poles shall be plotted in an equal area stereonet and contoured to get the maximas of pole concentrations. The failure modes can be identified from the pattern of maximas of pole concentrations [Fig. 1(a), (b) and (c)].

## 3.3 Determination of Adjustment Rating for Rock Slopes

The adjustment rating for joints in rock slopes is a product of the following three factors:

- i)  $F_1$  = Which is dependent on parallelism between the slope and the discontinuity.
- ii)  $F_2$  = Which is dependent on the dip of discontinuity.
- iii)  $F_3$  = Which is dependent on the relationship of dip of discontinuity and inclination of slope.

#### NOTES

1 Discontinuity refers to the planer discontinuity or the line of intersection of two planer discontinuities whichever is important from the point of view of instability of rock slopes.

2 The effect of ground water on the SMR has been considered indirectly by RMR<sub>basic</sub>.

3 The SMR shall not be applicable where length of joints along dip direction is less than 5 percent of affected slope height.

Table 2 gives ratings for  $F_1$ ,  $F_2$  and  $F_3$ . The notations are as follows:

- $\alpha_s$  = dip direction or inclination direction of the slope face.
- $\beta_s$  = dip or inclination of slope face.
- α<sub>j</sub> = dip direction of discontinuity in the case of planer slide.
   plunge or dip-direction of line of intersection of the unstable wedge.
- $\beta_j$  = dip of discontinuity in the case of planer slide.
  - plunge or dip of line of intersection of the unstable wedge.
- P = planer failure or wedge failure.
- T =toppling failure.



FIG. 1 REPRESENTATION OF STRUCTURAL DATA CONCERNING THREE POSSIBLE SLOPE FAILURE MODES IN ROCKS BASED ON STEREONET PLOTTING

(Cruuses 5.5 and 5.6, and 140re 5)						
Case		Very Favourable	Favourable	Fair	Unfavourable	Very Un- favourable
P	$ \alpha_j - \alpha_s $	>30°	30°-20°	20°-10°	10°-5°	<5°
Т	$ \alpha_j - \alpha_s - 180^\circ $					
P/T	$F_1$	0.15	0.40	0.70	0.85	1.00
<u>P</u>	<i>B</i> j	<20°	20°-30°	30°-35°	35°-45°	>45 '
Τ	<i>F</i> <sub>2</sub>	0.15	0.40	0.70	0.85	1.00
P/T	F <sub>2</sub>	1	1	1	1	1
P	$\beta_j - \beta_s$	>10°	10°-0°	0°	0°-(-10°)	<-104
Т	$\beta_j + \beta_s$	<110°	110°-120°	>120°	_	
P/T	F3	. 0	6	-25	50	-60

Table 2	Adjustme	nt Rating f	or Joints
(Clau	ses 3.3 and	$13.6$ , and $\Lambda$	lote 3)

= plane failure. P

= toppling failure. T

= slope dip direction. a

= slope dip. β.

= joint dip direction. αj = joint dip.

βi

The adjustment rating for the method of excavation  $F_4$  depends on whether the slope under investigation is a natural one or excavated by pre-splitting,

smooth blasting, mechanical excavation or poor blasting as given in Table 3.

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(0						
Method	Natural Slope	Presplliting	Smooth Blasting	Blasting or Mechanical	Deficient Blasting	
F4	+15	+10	+8	0	-8	
			SN	$MR = RMR_{basic} + ($	$(F_1 \times F_2 \times F_3) + F_4$	

## Table 3 Adjustment Rating for Methods of Excavation of Slopes (Clause 3.3)

#### 3.4 Estimation of Slope Mass Rating

The product of  $F_1$ ,  $F_2$  and  $F_3$  as well as  $F_4$  shall be added to RMR<sub>basic</sub> ratings to obtain slope mass rating (SMR).

Slope mass rating (SMR) = RMR<sub>basic</sub> +  $(F_1 \times F_2 \times F_3) + F_4$ 

On the basis of the values of slope mass rating the stability of rock slopes should be classified as fully stable (81-100), stable (61-80), partially stable (41-60), unstable (21-40) and very unstable (<20) as given in Table 4.

#### 3.5 Remedial Measures

Accordingly the very unstable cut slope may

require re-excavation, unstable slope may need extensive corrective measures, partially stable slopes may have to be supported with systematic supports such as rock bolts, and rock anchors and stable to fully stable slopes may need occasional to no supports.

#### 3.6 Cut Slope Angle (Slope Height $< 2^{\circ}$ m)

Safe cut slope angle can be determined from Table 2 by varying slope angle  $B_8$  till SMR of cut slope is more than 60. In weaker rocks cut slope angle may be taken equal to or less than apparent dip/dip of discontinuity in planer slide or dip of line of intersection of unstable wedges wherever excavation is feasible.

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Table 4	Tentative Description of SMR Classes
	(Clause 3.4)

Class No.	v	IV	III	II	Ι
SMR	0-20	21-40	41-60	61-80	81-100
Description	Very bad	Bad	Normal	Good	Very Good
Stability	Completely unstable	Unstable	Partially stable	Stable	Completely stable
Probable Type of Failure	Big planar or rotational	Planar or big wedge	Planar or many wedges	Biocks	None
Support	Re-excavation	Important corrective measures	Systematic supports	Occasional supports	None

#### ANNEX A (Foreword) COMMITTEE COMPOSITION

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#### **Amendments Issued Since Publication**

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